# **Welcome to the EASA AI Days High-Level Conference**! Day 2: MLEAP Stakeholders' Day 17<sup>th</sup> May 2023





MLEAP PROJECT – STAKEHOLDERS DAY #2

# Welcome to the EASA AI Days High-Level Conference ! Day 2: MLEAP Stakeholders' Day

# Guillaume Soudain - EASA Al Programme Manager





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# MLEAP STAKEHOLDERS DAY

### Paving the way for the future of Artificial Intelligence in Aviation

EASA

LABORATOIRE NATIONAL DE MÉTROLOGIE ET D'USSAIS

numalís

**MLEAP project:** [Machine Learning Application Approval]

May 17<sup>th</sup> 2023



# Agenda

- Introduction of the MLEAP project and of the Partners
- Presentation of the use cases
- Presentation of the single public deliverable
- Q&A session

#### COFFEE BREAK

- Presentation of the objectives and progress of Task 1
  (data management) Swen RIBEIRO, LNE
- Presentation of the objectives and progress of Task 2 (generalisation guarantees) Thiziri BELKACEM – Jean-Baptiste ROUFFET, Airbus Protect
- Presentation of the objectives and progress of Task 3 (robustness guarantees) Arnault IOUALALEN, NUMALIS
- Conclusions & Next Steps
- Networking Lunch



# Who we are > > >

### **Consortium members :**



EASA

Willy Sigl, Xavier Henriquel, Guillaume Soudain, François Triboulet

AIRBUS

PROTECT

**Airbus Protect** 

Michel Kaczmarek, Thiziri Belkacem, Jean-Baptiste Rouffet, Jeremy Bascans, Matthieu Rochambeau LABORATOIRE NATIONAL DE MÉTROLOGIE ET D'ESSAIS

LNE

**MLEAP** 

Team

**Olivier Galibert, Swen Ribeiro,** Agnes Delaborde, Sabrina Lecadre



Numalis Arnault Ioualalen, Noémie Rodriguez

AIRBUS



# Founded in 1901 - Appointed by French government on testing, certification and metrology for Industry (all sectors)

950+ systems evaluated in all major domains of AI and robotics since 2008





Development of softwares for AI evaluation and data preparation



www.lne.fr/logiciels/lne-matics

**Certification for AI processes (2021)** 



https://www.lne.fr/en/service/certification/certification-processes-ai

LEIA 1/2/3: testbeds for AI and robotics (simulation, physical, hybrid)





#### Numalis, the no-guess company

- Formal methods for AI systems
- Markets: Aeronautic, Defence, aerospace, railway, health
- SaaS solution to
  - Measure robustness
  - Explain behavior
  - Prepare compliance of IA
- 20 persons, Montpellier



On-going projects: HE MLEAP with EASA 2 EDIDP (Defence) ESA...





#### AIRBUS

# / Airbus Protect an

Consulting

: What we do

on Safety, Cybersecurity and Sustainability to optimise performance and support our customers on regulatory compliance and certification

#### Innovation

We are involved in research projects & member of institutional working groups

### We are a recognised training organisation

#### Software

Specialised software supporting endto-end safe mobility activities

# {Airbus} company

bringing together outstanding expertise in safety, cybersecurity and sustainability we created a European leader in risk management

... delivering consulting, services & solutions

#### **R&T & software development projects in AI:**

DEEL project for IRT Saint Exupéry and ANITI Confiance AI project EPI project for IRT SYSTEMX (Consortium with STELLANTIS, NAVAL Group, EXPLEO, LIP6) PRISSMA project for French Ministry of Transportation

# Day 2: MLEAP Stakeholders' Day Introductory notes from EASA technical team

Guillaume Soudain EASA AI Programme Manager MLEAP Project Sponsor Xavier Henriquel EASA Safety Expert MLEAP Tech Lead

François Triboulet EASA ATM/ANS Expert Coordinator



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# EASA AI Roadmap – Towards AI trustworthiness

- $\rightarrow$  Impact on all aviation domains
- → Common issues for safety-related applications
- $\rightarrow$  « AI trustworthiness » concept is the key!







# EASA guidance for Level 1 & 2 ML\* applications



# **EASA** Trustworthy AI building blocks Al Assurance AI **Trustworthiness** Human Factors for Al Analysis Al Safety Risk Mitigation



#### \* ML = Machine Learning

# **TOP3 challenges for Level 1&2 ML guidance**

- Anticipate means of compliance for Learning Assurance objectives on ML Model guarantees (generalization and robustness)
   →Exploit the Horizon Europe Research project MLEAP on 'Machine LEarning applications APproval'
- 2. Operational explainability & human centric aspects of AI

→Foster trust in the human-AI teaming by developing specific Human Factors guidance.

3. Ethics-based assessment – social & societal aspects
 →Evaluate and refine guidance based on use cases







# W-shaped assurance process





# W-shaped assurance process





## Machine Learning Application Approval (MLEAP) project

### **Objectives**

*"Streamline certification and approval processes by identifying concrete means of compliance with the learning assurance objectives of the EASA guidance for ML applications* 

### **Budget**

1.475 Million Euros funded by EU Horizon Europe

<u>Timeline</u> May 2022 - May 2024

### Research consortium

Airbus Protect - LNE - Numalis





## What is MLEAP project ?





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## **MLEAP Task 1 - Data completeness and representativeness**

- Data quality is a challenge due to inherent costs
- Data completeness and representativeness are usually not addressed per se:
  - Almost no dedicated tools
  - Tradeoff between representativity and diversity
  - ...But crucial to AI/ML performances & guarantees





## **MLEAP Task 2 - Generalization guarantee**

- Ability of AI/ML to scale up to unseen data during training is one of main concern with safety critical applications
- This task aims at defining protocols and strategies to enhance the ability of released models to generalize well

... accounting for data quality and volume and obtaining quantifiable guarantees.





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## **MLEAP Task 3 – Algorithm and model robustness**

- Aligning existing concepts and definitions between EASA <u>Concept</u> <u>Paper</u>, CoDANN <u>I</u> & <u>II</u> IPCs and ISO/IEC 24029
- Variety of approaches available: Empirical, statistical and formal methods
- Part of the ongoing effort of evaluating formal methods benefits (e.g. EASA-Collins Aeropsace <u>ForMuLA</u>IPC)





## **MLEAP - Pathfinder for future approvals**

- Practical aviation AI/ML use cases
  - EASA access to detailed models
  - & datasets
  - Public data/examples used when possible to allow comparison with 3<sup>rd</sup> parties
- Knowledge sharing
  - Events organized every 6 months
  - Project page with latest results
  - Public reports
- EASA AI Concept paper regularly updated with MLEAP outputs





## **MLEAP project milestones**



### **MLEAP – Presentation of the Use Cases**

#### **Objective:**

Lead and support the methods/tools selection process: Data qualification, Models evaluation, and Performance verification

Perform a comparative evaluation, of selected methods and tools, to assess their efficiency Help making recommendations for possible means of compliance



Speech to text STT - ATC



Automated visual inspection AVI



Collision avoidance ACAS - Xu



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### MLEAP – Use Cases Description> > >

#### **Speech-To-Text for Air Traffic Control (ATC-STT)**

>Objective: correctly translate spoken instructions ATCO to text for safer monitoring

- Language Understanding (LU): (Raju et al., 2021) systems provide both text and semantics associated with every input utterance.
- Spoken Instruction Understanding (SIU): (Lin, 2021) correctly interpret the ATCO instructions communicated between the control tower and the pilots
- VoicePrint Recognition (VPR): (Saquib et al., 2011) or Speaker Recognition Systems (SRS), aim to validate a user's claimed identity using characteristics extracted from their voices





### MLEAP – Use Cases Description> > >

### **Speech-To-Text for Air Traffic Control (ATC-STT)**

#### >Model & Data:

From Airbus internal project & open-source data/models

#### Data (utterances + transcriptions):

Airbus data: ATC interactions, in English, 100h French accent, 50h Chinese accent Open Source: real (ATCO2, UWB, NIST LDC-ATC), simulated (ATCO Sim), several accents (Chinese, French, German, Slo

Australian).

US, ~44h30min

#### Models (classical and DL-based)

Airbus models: Kaldi STT models implemented with VOSK, accent/callsign models (DNN classifiers) Open Source models: DL models, based on transformers <u>facebook/wav2vec2-</u>

large-960h-iv60-self

MLEAP Challenges: robustness toward noise and different accents, accents detection, Callsign detection



### MLEAP – Use Cases Description> > >

### **Automatic Visual Inspection (AVI)**

**Objective:** « help operators to perform the in-service damage detection, to reduce the aircraft maintenance duration, for scheduled and unscheduled events."

Model & Data: from Airbus internal project & open-source (TBC)

Data: are made of two main parts, lightning strikes and dent impacts, with data augmentation (Changyu et al., 2014);

Acquisition of pictures is done from cameras and downloaded to the design/deployment environment; Labelling is done using the VOTT tool, where every image can contain several damages of different classes;

Weighting samples to cope with imbalanced data sets

Model: is made of Siamese network constructed for a multitasking framework;

Aims to detect both the damage type (dent impact or lightning strike) and its characterization (severity level);

Using openCV library

#### **MLEAP Challenges:**

Automatic detection of external damages and their classification into two types: lighting strike impacts and dents;

It is an on-going project, materials (metrics, models and data) are still under development

Find acceptable metrics to bring computer vision models to human abilities on surface damage detection

First targeted performance: >95% accuracy correctly detecting damages



Dents Damages (1)



Lightning Strike impacts (2)

- 1) <u>https://www.researchgate.net/figure/Wing-skin-metal-dentexamples\_fig3\_331961295</u>
- https://www.researchgate.net/figure/Structural-damage-inthe-outer-skin-in-the-Airbus-A400-M-airplane-after-thelightning\_fig8\_305817924

### MLEAP – Use Cases Description > > >

Next-Generation <u>Airborne Collision Avoidance System</u> for <u>Unmanned aircrafts</u> (ACAS Xu)

#### **Objective:**

ACAS is a universal system-to-system collision avoidance It issues horizontal turn advisories to avoid an intruder aircraft Leverage NNs to solve ACAS problems (Bak and Tran, 2022)

#### Model & Data:

The data consists of different entries of the LUTs from the <u>RTCA SC-147 MOPS</u> The chosen action shall minimize the probability of collision:

- $\circ$   $\rho$  (ft): Distance from ownship to intruder
- $\circ$   $\theta$  (rad): Angle to intruder relative to ownship heading
- $\circ$   $\psi$  (rad) : Heading angle of intruder relative to ownship heading direction
- vown (ft/s) : Speed of ownship
- vint (ft/s) : Speed of intruder
- $\circ$  T (s) : Time until loss of vertical separation

#### **MLEAP Challenges:**

In a context where the complete ODD is known, data quality is highly dependent on the LUTs Models generalization & robustness are evaluated based on the ability of the model to correctly compress LUTs





ML model elements of the ACAS Xu system

https://www.eurocontrol.int/publication/airborne-collision-avoidance-system-acas-guide



### **MLEAP Report**

First version of the MLEAP deliverable, next and last version in a year.

A nice 260 pages document.





### **MLEAP – Report – The Topics**



Representativeness and Completeness Corner cases and outliers



### Models

#### **Generalization properties**





### **MLEAP – Report – The common steps**

#### Definitions

What are the meanings of the terms What do the various documents (standards, CP, ...) define What meaning do we choose for the report

#### Experimentation

How the tools and methods actually behave with various data or models Experiment around scaling Try with aviation use-cases

#### State of the Art

Review of scientific littérature Review of existing methods and tools Construction of selection grids to associate use-cases and methods/tools

Projection into the W-shaped process Generalize the methodologies as much as reasonably possible Structure inputs for use by the EASA in their works

### **MLEAP** – Report – The document





### **MLEAP – Report – The next steps**

Complete the selection grids Complete the experimentations

Consolidate the projection to the W-shaped process

Apply the methods to the use cases

Listen to the feedback from all of you

ai@easa.europa.eu



### MLEAP – Task #1 milestones: Data Completeness & Representativeness

**Completeness**: A data set is complete if it sufficiently covers the entire space of the operational design domain for the intended application.



**Representativeness**: A data set is representative when the distribution of its key characteristics is similar to the actual input space of the intended application



Task #1 : Data Completeness and Representativeness

#### Task #1 objectives (so far)

State-of-the-art: Provide a list of factors influencing the choice of tools and approaches in order to assess the completeness and representativeness of databases, with corresponding justifications and bibliographical references.





Task #1 : Data Completeness and Representativeness

### Task #1 objectives (so far)

- State-of-the-art: Provide a list of factors influencing the choice of tools and approaches in order to assess the completeness and representativeness of databases, with corresponding justifications and bibliographical references.
- Synthesis: Present a draft structure of the selection grid for the assessment tools and methods.





Task #1 : Data Completeness and Representativeness

### Task #1 objectives (so far)

- State-of-the-art: Provide a list of factors influencing the choice of tools and approaches in order to assess the completeness and representativeness of databases, with corresponding justifications and bibliographical references.
- Synthesis: Present a draft structure of the selection grid for the assessment tools and methods.
- Testing: Identification or development of efficient and practicable methods and tools for the assessment of completeness and representativeness of data sets (training, validation and test) in the generic case of datadriven ML.


# MLEAP – Task #1 Technical Feedback > > >



Task #1 : Data Completeness and Representativeness

# State-of-the-art: influence factors identified

#### **Technical requirements**

- Intended behavior
- Model architecture
- Data dimensionality
- Intended level of autonomy
- Intended level of performance
- Intended level of robustness and resilience
- Intended level of stability

#### **Processes**

- Data Management requirements (specs)
- Data Quality improvement (augmentation...)
- Data synthesis
- Data sampling
- Labelling
- Pre-processing

#### Other DQRs

- Balance
- Relevance
- Diversity (discriminative power)
- Diversity (absence of non representative sampling bias)
- Currentness

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# MLEAP – Task #1 Technical Feedback > > >



Task #1 : Data Completeness and Representativeness

# Main take aways of the state-of-the-art

# Assessment of data quality in general lacks maturity in the field of AI:

< 10 works are explicitly considering influence factors in their relationship to Completeness/Representativeness Influence factors and target properties are not studied in a structured way Exhaustive data quality of the data set may be actually hard and challenging to attain

Operations required to enhance data quality attributes may be mutually exclusive (e.g. ensuring relevance can be detrimental to representativeness) Importance of expert contextual trade-off



# MLEAP – Task #1 Technical Feedback > > >



Task #1 : Data Completeness and Representativeness

# Main take aways of the state-of-the-art

*In literature, the burden of sorting the wheat from the chaff often still rests on the model.* 

No "off-the-shelf" method to quantify the relationship between a factor of influence and Completeness/Representativeness. High-dimensionality challenges rarely addressed. Adaptability of the methods to high-dimensional data needs to be explored.



# MLEAP – Task #1 Technical Feedback > > >

## Synthesis: Building the selection grid

# 80+ sources explored, among which 60+ assessment methods analysed



Sufficient maturity In line with the project objectives



Task #1 : Data Completeness and Representativeness

#### 6 methods selected (from 11 identified)

#### Processes

• Data Management requirements (2 methods)

Intended level of robustness and resilience

- Data Quality improvement (3 methods)
- Data synthesis (1 method)

Technical requirements

Intended function Model architecture

Data dimensionality

Intended level of autonomy Intended level of performance

Intended level of stability

- Data sampling (1 method)
- Labelling (2 methods)
- Pre-processing

### **Other DQRs**

- Balance (1 method)
- Relevance
- Diversity (discriminative power)
- Diversity (absence of bias) (1 method)
- Currentness (1 method)

#### 11 methods selected (from 33 identified)

3 methods selected (from 18 identified)

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# MLEAP – Task #1 Technical Feedback > > >

## **Testing Phase**



Task #1 : Data Completeness and Representativeness

## PCA

- Test task: Classification
- Associated UC: ACAS-Xu
- Test data sets
  - ACAS-Xu
  - Gas sensor array (external)



# MLEAP – Task #1 Technical Feedback > > >

## **Testing Phase**



Task #1 : Data Completeness and Representativeness

#### PCA

- Test task: Classification
- Associated UC: ACAS-Xu
- Test data sets
  - ACAS-Xu
  - Gas sensor array (external)

## PCA

- PCA highlighted particularities of the ACAS-Xu dataset
- Triggered further investigations
- Note: ACAS-Xu is probably at the edge of relevance for this method



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# MLEAP – Task #1 Technical Feedback > > >

## **Testing Phase**



Task #1 : Data Completeness and Representativeness

#### PCA

#### **Entropy (Shannon)**

- Test task: Image Segmentation
- Associated UC: AVI
- Test data sets
  - CIFAR-100 (external)
  - ROSE (LNE)



# MLEAP – Task #1 Technical Feedback > > >

## **Testing Phase**



Task #1 : Data Completeness and Representativeness

### PCA

#### **Entropy (Shannon)**

- Test task: Image Segmentation
- Associated UC: AVI

Test data sets

- CIFAR-100 (external)
- ROSE (LNE)

- Can be used at different level (label-wise, pixelwise...)
- Provides coarse-grain information
- Should preferably be combined with other metrics (yet to be determined)





# MLEAP – Task #1 Technical Feedback > > >

## **Testing Phase**



Task #1 : Data Completeness and Representativeness

#### PCA

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- Test task: Image Segmentation
- Associated UC: AVI
- Test data sets
  - CIFAR-100 (external)
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- Can be used at different level (label-wise, pixelwise...)
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# MLEAP – Task #1 Technical Feedback > > >

## **Testing Phase**



Task #1 : Data Completeness and Representativeness

### PCA

### Graph (feature combination distribution)

- Test task: Classification
- Associated UC : ACAS-Xu
- Test data set
  - Titanic (external)



# MLEAP – Task #1 Technical Feedback > > >

## **Testing Phase**



Task #1 : Data Completeness and Representativeness

#### PCA

#### Graph (feature combination distribution)

- Test task: Classification
- Associated UC : ACAS-Xu
- Test data set
  - Titanic (external)

#### Entropy

#### Graph

- Results are easy to interpret
- Can be used as an efficient visual tool (like PCA)
- Must be tested at scale





# MLEAP – Task #1 Technical Feedback > > >

## **Testing Phase**



Task #1 : Data Completeness and Representativeness

### PCA

Graph (feature combination distribution)

# Sample similarity (Degree of Correspondence)

- Test task: Speech recognition
- Associated UC: ATC-STT
- Test data set
  - Fluent Speech Commands (external)



# MLEAP – Task #1 Technical Feedback > > >

## **Testing Phase**



Task #1 : Data Completeness and Representativeness

### PCA

Graph (feature combination distribution)

# Sample similarity (Degree of Correspondence)

- Test task: Speech recognition
- Associated UC: ATC-STT
- Test data set
  - Fluent Speech Commands (external)

#### Entropy

#### Sample similarity

- DoC is inconsistent and intractable on speech embeddings
- This specific method will be put aside
- Similarity-based analysis remains interesting

# MLEAP – Task #1 Technical Feedback > > >

## Main take aways of the testing phase



Task #1 : Data Completeness and Representativeness

No method is **self-sufficient** They need to be combined to provide meaningful insight No method is **universal** The method and their combination must be tailored to each type of task/data



Completeness and representativeness can only be estimated w.r.t ODD specifications **No "absolute measure"** 

Trade-off between completeness and representativeness for e.g. corner cases





Task #1 : Data Completeness and Representativeness

# Next step for Task 1 Adapting identified methods to work on high scale datasets Continue to test methods of the selection grid

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# **MLEAP – Task #2 Milestones: Model development**

# **Generalization properties**

State-of-the-art analysis:

Available methods and tools to evaluate generalization bounds; Barriers in generalization guarantees: ML and DL; Limitation of available methods and common practices;



Identification/selection of suitable methods: Methods selection; Projection into the W-shaped approach: ML development pipeline;

**Experimentation & Evaluation** 

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# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >

## Supervised machine learning



Training: optimize algorithm parameters to minimize errors on the examples

## Machine learning:

- $\circ$  Approximation
- Optimization
- Estimation

Generalization: We are expecting few errors on unseen data. It is based on the assumption that we have regularities behind the data .



Task #2 : Model

generalization

# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >

Generalizability

#### Definition

Model's ability to generalize the learned knowledge to a new context or environment

#### **Success estimator**

Statistical tools that estimate how well the model generalizes to unseen data

For  $\delta \epsilon (0,1)$  the generalizability of model  $\hat{f} \epsilon F$  on w.r.t. data set D is:

$$G(\hat{f}, D) \leq \sqrt{\frac{func(model \ class \ F \ complexity) + \log(1/\delta)}{\|D_{train}\|}}$$

## **Success indicator**

- Evaluation-based: Good performances (w.r.t. some criteria) for Dtest ≠ Dtrain
- Testing-based: correctness of results during adversarial attacks and spot failure modes

Generalization Guarantees		Algorithm Dependent		
		Yes	No	
Data	Yes	<ul> <li>PAC-Bayesian</li> <li>PAC-Bayesian bounds for NNs</li> <li>(+) more precise, better distributional properties of the learning algorithm</li> </ul>	<ul> <li>Rademacher Complexity (RC)</li> <li>RC and regularized Empirical Risk Minimization (ERM)</li> <li>(+) better estimation</li> </ul>	
Dependent	No	<ul> <li>Model Compression</li> <li>Based on Model Distillation</li> <li>(-) do not take into account data features</li> <li>(+) focuses on the model enhancement</li> </ul>	<ul> <li>VC-dimension</li> <li>VC-dimension for NNs</li> <li>(-) Not practical for particular use-cases (Dar et al., 2021)</li> <li>(+) widely applicable</li> </ul>	
	•	Statistical guarantees O Data statistics O Error gradient during trainir Geometry analysis bounds (combining mapping)	ng ng input, output spaces and the	





Task #2 : Model generalization



Task #2 : Model generalization

# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >

**Generalization Bounds** 

**Objective:** bounding the deviation of the true risk of the learned hypothesis from its empirical measurement

$$\forall \mathcal{D} \quad \mathbb{P}[|L_D(W) - L_{\mathcal{S}}(W)| \leq \varepsilon(\mathcal{H}, m, \delta, \mathcal{D}, \mathcal{S}, Optim, W)] > 1 - \delta$$

 $\mathcal{D} \sim \mathcal{S}$ 

Generalization bound

Several bounds are defined in the littérature based on different theoretical framework, such as:

- Uniform convergence based (Sharpness-based measures)
- Uniform stability based
- Algorithm robustness based
- Mutual information
- Measures related to the optimization procedures

For example: bound based on VC dimension

$$\varepsilon \to \varepsilon(\mathcal{H}, m, \delta) \sim \mathcal{O}\left(\sqrt{\frac{VCdim(\mathcal{H}) + ln(\frac{2}{\delta})}{m}}\right)$$

Algo.	Ref.	Bound
CNN	(Lin and Zhang, 2019)	$R_{\mathcal{D}}(F_{\mathcal{C}}) \leq \hat{R}_{S,l_{\eta}}(F_{\mathcal{C}}) + \mathcal{O}\left(\left(\frac{\ X\ _{F}\mathcal{R}_{\mathcal{C}}}{\eta}\right)^{\frac{1}{4}}n^{-\frac{5}{8}} + \sqrt{\frac{\ln(1/\delta)}{n}}\right)$
RNN	(Chen et al., 2019)	$R(f_t) \leq \hat{R}(f_t) + \tilde{O}\left(\frac{L \times Complexity}{\sqrt{m}} + B\sqrt{\frac{\log(1/\delta)}{m}}\right)$
NN for classification	(P. Jin et al., 2020)	$\varepsilon(f) \leq \frac{\sqrt{d}. (1 - \rho_{\tau})}{\min(\delta_0, \kappa \delta_{\tau})} = \alpha(\tau). CC(\tau)$
NN	(Alquier, 2021)	Catoni's bound (PAC Bayes) $\mathbb{P}_{s}\left( \forall \rho \in \mathcal{P}(\Theta), \mathbb{E}_{\theta \sim \rho}[\mathcal{R}(\theta)] \leq \mathbb{E}_{\theta \sim \rho}[r(\theta)] + \frac{\lambda C^{2}}{8n} + \frac{kL(\rho  \pi) + \log \frac{1}{\epsilon}}{\lambda} \right) \geq 1 - \epsilon$
	(Alquier, 2021) (McAllester, 1998)	$ \begin{array}{l} \text{Mc Allester's bound} \\ \mathbb{P}_{s}\left( \forall \rho \in \mathcal{P}(\Theta), \mathbb{E}_{\theta \sim \rho}[\mathcal{R}(\theta)] \leq \mathbb{E}_{\theta \sim \rho}[r(\theta)] + \sqrt{\frac{KL(\rho) \pi) + \log \frac{1}{\epsilon} + \frac{5}{2}\log(n) + 8}{2n - 1}} \right) \geq 1 - \epsilon \end{aligned} $

17 bounds selected based on:

- genericity of the bound
- Use cases applicability

## AIRBUS

# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >

Al issues: from problem analysis to model release

Modeling, Training, Evaluation/Testing, Adjusting, re-training, validating, preparing for release (embedding), behavior analysis ...

## Misunderstanding of the generalization bounds

KPIs

- Some norm-based measures negatively correlate with generalization
- Conventional bounds based on uniform convergence or uniform stability are inadequate for over-parameterized models

### Common mistakes and pitfalls in practice

- Inappropriate training objective
- Inappropriate data representation, volume, split (train, test, valid), quality (noisy, high sparsity)
- Inappropriate model complexity to perform the task, and evaluation metrics

## Gap between expectations from evaluation vs the real-world application

- How far away the empirical assessment reflects the reality about the model efficiency?
- Appropriate performance indicators to the application domain cannot ALWAYS be translated by existing evaluation metrics
- How to define a good model ? what constitutes a good AI/ML model?
- What about the uncertainty tolerance: how a 85% accuracy is good? how the 15% uncertainty is tolerable?
- How the final model will behave in the target system/environment?

## Unhandled ML/DL testing limitation and challenges

- How to define exhaustively the testing scenarios? How to deal with "black boxes in DL"?





Task #2 : Model

generalization

Good model

# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >



Task #2 : Model generalization

## Towards application independent ML development pipeline to promote generalizability

### **Objectives**

### Deal with models overfitting/underfitting in industry

- Regularization techniques, training adaptation (warm-up and fine-tuning)
- Model/Network architecture and complexity adequacy with the target task

#### Bridge the gap between experimentation and industrial expectation

- Adopt a multicriteria/additional validation phases;
- Include KPIs (industrial target performance) in the learning objectives and the evaluation metrics as well
- Leverage ML testing properties to promote the quality assurance and help to identify defects and flaws

### Better handle the OOD samples and reduce the impact on the safety of the AI system

Deal with rare cases with high impact on the confidence of the model, in order to minimize the risks.

# Build an enhanced data and model development pipelines reducing the impact of common practices and pitfalls that result in a weak generalization ability of an ML/DL model, after release/implementation



# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >



Task #2 : Model generalization

## **Target application definition**

$$D \xrightarrow{T_f} (X, Y), \quad with$$

$$T_f(d) = (x, y), \quad and \quad x \in X \text{ and } y \in Y$$

$$\begin{cases} f \in F, & (1) \\ X : x_i = [x_i^0, \dots, x_i^n], & (2) \\ Y : y_j = [y_j^0, \dots, y_j^m], & (3) \\ f : X \xrightarrow{f(x)} Y, & (4) \\ M = \{m_1, \dots, m_k\}, & (5) \\ B = \{b_1, \dots, b_l\}, & (6) \\ b_t(m_t \circ f(x_t)) \in \{0, 1\} & (7) \\ E = \{e_1, \dots, e_z; (e_i \odot x_i) = x'_i\} (8) \end{cases}$$

- 1) The selected model
- 2) The input space
- 3) The output space
- 4) The mapping function
- 5) Set of SMART objectives & metrics to evaluate their achievements
- 6) Verification scheme and target performances validity/acceptance indicators
- 7) Benchmarking of the model w.r.t (6)
- 8) Elements and/or conditions that directly impact the inputs, and hence the outputs after implementation.



# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >

Task #2 : Model generalization

## **ML Pipeline / W-shaped process projection**

- (1) Data evaluation and qualification (<=> Task#1)
  - a. Minimal size of data set needed
  - b. Data quality evaluation (completeness, representativeness)
  - c. Enhancement operations: data augmentation, processing, cleansing, balancing, and splitting;



## AIRBUS

# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >



Task #2 : Model generalization

## **ML Pipeline:**

## (2) Model development and adaptation

- a. Data Constraints: data size and type, alignment, balance ...
- b. The mappings between the inputs and outputs
- c. Generalization bounds estimation ;





# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >



Task #2 : Model

generalization

**ML Pipeline:** 

- (3) Model training on the optimized data set (<=> Task#3)
  - a. Benchmark including a set of industrial KPIs
  - b. Adapted evaluation measures/metrics/thresholds
  - c. A posteriori evaluation of the trained model: generalization & robustness
  - d. Measures and loss functions should be adapted to meet the target application objectives







# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >

Task #2 : Model generalization





# **MLEAP – Task #2 Milestones : Model development – Generalization** properties > > >



Task #2 : Model generalization

## Experimentation: ATC-STT Task – Models evaluation

## **Datasets:**

- AIRBUS dataset (real ATC exchange from French airports)
  - Open-source datasets (from European airports)

## Models:

- AIRBUS model, based on the <u>Vosk API</u> & <u>Kaldi</u> (no Deep Learning), trained on AIRBUS dataset (FR accent included)
- Open-source DL models, based on a transformers architecture, trained on the open-source datasets, fine-tuned in AIRBUS data

## **Evaluation metric:**

- Word Error Rate (WER) =  $\frac{S+D+I}{N}$ 

- S is the number of substitutions
  - *D* is the number of deletions
  - *I* is the number of insertions
- N is the total number of words in the reference

# **Evaluation Objectives**

- Analysis of the development pipelines to identify the limitations;
- Analysis of the data quality & volume w.r.t. target performance:
- Analysis of the evaluation schemes: metrics, KPIs, 3. training objectives ...;
- Compare the estimated generalizability VS the real 4. performances;
- Make suggestions: metrics, data OPs, methods to improve existing results and pipelines;
- Validate the suggestions on real-life use-cases. 6.

- Accuracy = 1-WER



# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >



### **AIRBUS Vosk Model vs DL Open-source**

Excellent performances of the AIRBUS model on the AIRBUS data set and **poor** performances on open-source data sets **Possible bias:** 

- $\rightarrow$ Source of data (from a few French airports)
- $\rightarrow$ Audio quality (noise, microphone used,...)
- $\rightarrow$ Model architecture and implementation (Vosk API & Kaldi)

Open-source models are trained on larger data sets, and their complexity is more important, but performance on AIRBUS data are average. High-performance on open-source data, regardless of the recording context (accent, noise, etc.) and therefore more robust

#### **Transfer Learning**

 $\rightarrow$ Zero-shot evaluation

→ Fine-tuning on the AIRBUS data

Models	Data	AIRBUS data set	ATCO2	ATCOSIM	UWB
AIRBUS Model Vosk		11.50%	91.05%	95.05%	63.46%
Zero- shot	Jzuluaga/wav2vec2 -large-960h-lv60- self-1	34.63%	36.27%	6.82%	20.46%
	Jzuluaga/wav2vec2 -large-960h-lv60- self-2	34.89%	37.14%	22.98%	19.69%
Fine- tuned	Jzuluaga/wav2vec2 -large-960h-lv60- self-1	15.13%	35.81%	15.85%	30.96%
	Jzuluaga/wav2vec2 -large-960h-lv60- self-2	In progress			

Zero-shot evaluation results showing averaged WER of the models



Means that the model is trained in the Dtrain part of the data set



Task #2 : Model

generalization



# MLEAP – Task #2 Milestones : Model development – Generalization properties > > >

Task #2 : Model generalization

## **Experimentation: ATC-STT Task – Performance Comparison**



AIRBUS



Task #2 : Model generalization

# Next step for Task 2 Experimentation and Evaluation: General framework development and tests of identified bounds and methods

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# MLEAP – Task #3 Milestones: Algorithm and model robustness

Review of methods and tools

Review of methods to identify corner cases and abnormal inputs

Identification of sources of instabilities during the design phase

Identification of sources of instabilities during the operational phase

Demonstration on a use-case for the intended application





# MLEAP – Task #3 Milestones: Algorithm and model robustness> > >



## Why talking about robustness?

Task #3 : Algorithm and model robustness



## One of the key requirement from the HLEG



One of the key objective in the AI Act



Because it is one of the key issue with AI!



# MLEAP – Task #3 Milestones: Algorithm and model robustness> > >



Task #3 : Algorithm and model robustness

Why talking about robustness?

# Robustness means keeping the performances on the domain of ODD ODD in an open world can be challenging









Nominal case

# Variation of nominal case

## Adversarial case

A non-existent case



# MLEAP – Task #3 Milestones: Algorithm and model robustness> > >



Task #3 : Algorithm and model robustness

AIRBUS

**Robustness assessment approaches** 

How to ensure that the system still works when it should? Three types of approaches : statistical, formal, empirical



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# MLEAP – Task #3 Milestones: Algorithm and model robustness> > >



Task #3 : Algorithm and model robustness

# **Different ways of defining the concept**

#### Aligning several sources of the state of the art

- Different concepts robustness, stability, corner cases...
- Different requirements
- Different methods: statistical, formal, empirical

## Studying the maturity of the ecosystem

- Scalability of the methods
- Applicability to the relevant use-cases

## Preparing the application on the use case



Harmonized state of the art



# MLEAP – Task #3 Milestones: Algorithm and model robustness> > >



Stability (of the training algorithm, trained model and inference model)	$  x' - x   < \delta \Rightarrow   \hat{f}(x') - \hat{f}(x)   < \varepsilon$		
Bias (~ underfitting)	$bias^{2}(\mathcal{F},n) = \mathbb{E}_{x \sim \mathcal{X}} \left[ (\overline{f_{n}}(x) - f(x))^{2} \right]$		
Variance (~ overfitting)	$var(\mathcal{F}, n, x) = \mathbb{E}_{D \sim \mathcal{X}^n} \left[ \left( \hat{f}^{(D)} - \overline{f_n}(x) \right)^2 \right]$		
Relevance (~ explainability)	Acceptability of contribution of each dimension of the input vector		
Reachability	$\mathcal{E}^n\left(x,\hat{f}^n(x)\right)\notin Z$		



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Task #3 : Algorithm and model robustness


### MLEAP – Task #3 Milestones: Algorithm and model robustness> > >



Task #3 : Algorithm and model robustness

**Complementarity of methods** 

### Conceptual alignment is possible

- Stability around the nominal conditions
- Robustness to more difficult conditions
- Resilience to adverse conditions

#### Methods are complementary

- Depends on the ODD description
- Combining approaches to match the requirements
- ...but varying degree of scalability





**3** approaches at a glance

**Statistical** 

Easy to setup

Each allow specific advantages and drawbacks

### MLEAP – Task #3 Milestones: Algorithm and model robustness> > >



Rely on data sets

Local guarantees High dimensional sub-space

Formal

Require human intervention **Experimental protocol** 

Task #3 : Algorithm and model robustness



**Empirical** 





f(x)

### MLEAP – Task #3 Milestones: Algorithm and model robustness> > >



Different ways of exploring of the ODD Different level to define corner case in the ODD (context: automotive)

- Scenario (several instants)
- Scene (one instant)
- Objects
- Domain (weather)
- Pixel (camera)



(From Heidecker et al., 2021)



Task #3 : Algorithm and model robustness

### AIRBUS

### MLEAP – Task #3 Milestones: Algorithm and model robustness> > >

### A priori assessment of suitability

	Empirical methods	Statistical methods	Formal methods
Stability of the training algorithm			
Stability of the trained model			
Stability of the inference model			
Bias			
Variance			
Relevance			
Reachability			
Corner case exploration			

Scalability	Human intervention needed	Doable but through sampling	Doable but locally
Methods	<ul><li>Field trial</li><li>A posteriori</li><li>Benchmarking</li></ul>	Combining metrics	<ul><li>Solver</li><li>Abstract interpretation</li><li>Optimization</li></ul>

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Task #3 : Algorithm and model robustness





Task #3 : Algorithm and model robustness

### **Next step for Task 3**

# Applying a panel of suitable approaches on the different use cases to exemplify the guidance

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### Airbus Protect / Artificial Intelligence Days At Paris Air Show June 21<sup>st</sup> >>

June 21<sup>st</sup>:

Awareness session conference: from 10 to 11am at Airbus Pavillon - On Invitation only

### Knowledge Sharing Conference & Networking:

from 3 to 5pm - at VIPARIS Conference center - Conference Room N°2 -

### What's next for MLEAP Project?

Our partners:





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### WHAT's next for MLEAP?

**PROJECT: MLEAP Final report in 1 year from today EVENTS:** January 2024: MLEAP Stakeholders day #3 **Awareness session conference #2 April 2024: Knowledge sharing conference #2** May 2024: MLEAP Stakeholders day #4





https://www.easa.europa.eu/en/research-projects/machine-learning-application-approval https://events.airbus.com/airbus-protect-easa-paris-air-show/

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# {Thank you}

# **NETWORKING LUNCH!** Let's keep the party going!



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# Thank you for your participation!

# Let's continue the discussion until 14:00 around a lunch sponsored by AIRBUS PROTECT

### Any question? Please contact us: ai@easa.europa.eu





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